Solving Pasur Using GPU-Accelerated Counterfactual Regret Minimization*

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Abstract

Pasur is a fishing card game played over six rounds and is played similarly to games such as Cassino and Scopa, and Bastra ¹. This paper introduces a CUDA-accelerated computational framework for simulating Pasur, emphasizing efficient memory management. We use our framework to compute near-Nash equilibria via Counterfactual Regret Minimization (CFR), a well-known algorithm for solving large imperfect-information games.

Solving Pasur presents unique challenges due to its intricate rules and the large size of its game tree. We handle rule complexity using PyTorch CUDA tensors and to address the memory-intensive nature of the game, we decompose the game tree into two key components: (1) actual game states, and (2) inherited scores from previous rounds. We construct the Full Game Tree by pairing card states with accumulated scores in the Unfolding Process. This design reduces memory overhead by storing only essential strategy values and node connections. To further manage computational complexity, we apply a round-by-round backward training strategy, starting from the final round and recursively propagating average utilities to earlier stages. Our approach constructs the complete game tree, which on average consists of over 10⁹ nodes. We provide detailed implementation snippets to illustrate the structure and training logic of our framework and the CFR algorithm.

After computing a near-Nash equilibrium strategy, we train a tree-based model to predict these strategies for use during gameplay. We then estimate the fair value of each deck through large-scale self-play between equilibrium strategies by simulating, for instance, 10,000 games per matchup, executed in parallel using GPU acceleration. Our analysis reveals that the distribution of high-value cards heavily influences match outcomes, accounting for much of the variation in deck fairness. Finally, each trained model is lightweight, making it feasible to be used as a real-time AI agent for Pasur.

Similar frameworks can be extended to other reinforcement learning algorithms in settings where the action tree naturally decomposes into multiple rounds such as turn-based strategy games or sequential trading decisions in financial markets.

 $^{{\}rm ^*This\ preprint\ is\ available\ at\ URL:\ https://sinabaghal.github.io/files/SolvePasurviaCFR.pdf}$

¹Wikipedia: Pasur (card game)

1 Introduction and Background

Imperfect-information games pose significant challenges due to hidden information and strategic uncertainty. Counterfactual Regret Minimization (CFR) has emerged as a powerful algorithmic framework for approximating Nash equilibria in such settings, notably achieving success in poker variants and other complex card games [7, 3, 1, 2, 6]. By iteratively minimizing regret over possible strategies, CFR converges towards equilibrium policies without exhaustive search, making it an attractive method for large-scale sequential games.

In this work, we focus on *Pasur*, a traditional fishing card game popular in Middle Eastern cultures, with a six-round structure and unique scoring rules. Each round, players receive new cards while aiming to capture valuable cards from the table through matching and summation mechanics. Unlike many extensively studied games, Pasur has not been rigorously solved, in part due to its combinatorial complexity and memory-intensive game tree.

In this paper, we present a CUDA-accelerated implementation of CFR in Py-Torch tailored to Pasur, addressing its computational challenges by decomposing the game tree into game states and accumulated scores. Our approach computes the complete game tree, enabling near-Nash equilibrium calculations rather than relying on sampling methods. To further optimize GPU memory usage, we train the CFR models round-by-round in reverse order, propagating average utilities to ensure tractability. At any given time, only the tensors for the current round are kept on the GPU; all others are stored in CPU memory. Our carefully designed data structures made it possible to train and develop the entire CFR algorithm on a game tree with an average size of 10⁹, all within the constraints of a system with 32 GB of RAM and 10 GB of VRAM. After computing a near-Nash equilibrium strategy, we train a tree-based model to calculate the strategies for use during gameplay. These tree-model also facilites the estimation of deck fair values through self-play.

This framework not only advances the strategic understanding of Pasur and fishing card games more broadly, but also enables the development of practical AI agents capable of playing at near-optimal levels. Moreover, this document details the construction and update procedures of every step in the framework through CodeSnippets, including the implementation of the CFR algorithm.

Several clarifications about the CodeSnippets are in order. The CodeSnippets aim to convey as much detail as possible; however, certain operations are omitted for clarity. These include routine tasks such as data type conversions and the use of .clone() to avoid in-place modifications, if necessary. Additionally, we omit the torch. prefix in all code expressions. For example, torch.any(t_act[:,1,:], dim=1) is written as any(t_act[:,1,:], dim=1). It is also worth noting that not all lines of code are shown in the CodeSnippets. For complete implementations, we refer the reader to the GitHub repository². Finally, we use symbolic notation to simplify certain expressions. For instance, instead of t_1.repeat_interleave(t_2), we write t_1 \otimes t_2. Similarly, t_1 \otimes t_2 denotes the dimension-specific form

t_1.repeat_interleave(t_2, dim=1).

²Paper Homepage

1.1 Extensive Games and CFR

In Imperfect-Information Extensive-Form Games there is a finite set of players (\mathcal{P}) . A node h at time T is defined by all the information revealed at a , particularly the actions taken by players \mathcal{P} . Terminal nodes, denoted by \mathcal{Z} , are defined as those nodes where no further action is available. For each player $p \in \mathcal{P}$, there is a payoff function $u_p : \mathcal{Z} \to \mathbb{R}$. In this paper, we focus on the zero-sum two-player setting i.e., $\mathcal{P} = \{0,1\}$ and $u_0 = -u_1$.

Imperfect information is represented by information sets (infosets) for each player $p \in \mathcal{P}$. It is emphasized that at player p's turn at infoset I, all nodes $h, h' \in I$ are identical from p's perspective. In this situation, we say infoset I belongs to p and we denote the set of all such infosets by \mathcal{I}_p . Actions available at infoset I are also denoted by A(I). A strategy $\sigma_p(I): A(I) \to \mathbb{R}^{\geq 0}$ is a distribution over actions in A(I). The strategy of other players is denoted by σ_{-p} . We denote by $u_p(\sigma_p, \sigma_{-p})$ the expected payoff for p if players' actions are governed by strategy profile $\sigma := {\sigma_p}_{p \in \mathcal{P}}$.

Reach probability $\pi^{\sigma}(h)$ is defined as the probability of arriving at node h, if all players play according to σ . For $I \in \mathcal{I}_p$ and $h \in A(I)$, we denote by $\pi^{\sigma}_{-p}(h)$ the probability of arriving at h in the event where p chooses to reach h and other players follow σ . Define $\pi^{\sigma}_p(I) := \sum_{h \in I} \pi^{\sigma}_p(h)$ and $\pi^{\sigma}_{-p}(I) := \sum_{h \in I} \pi^{\sigma}_{-p}(h)$. Counterfactual utility at infoset $I \in \mathcal{I}_p$ is defined as

$$u^{\sigma}(I) := \sum_{h \in I, h' \in \mathcal{Z}} \pi^{\sigma}_{-p}(h) \pi^{\sigma}(h, h') u_p(h') \tag{1}$$

Similarly, counterfactual utility for $a \in A(I)$, $u^{\sigma}(I, a)$ is defined as in (1), except that p chooses a with probability 1 once it reaches I. Formally, if h.a denotes the node wherein action a is chosen at node h, then

$$u_p^{\sigma}(I,a) := \sum_{h \in I, h' \in \mathcal{Z}} \pi_{-p}^{\sigma}(h) \pi^{\sigma}(h.a, h') u_p(h') \tag{2}$$

Finally, in a two-player extensive game a Nash equilibrium [4] is a strategy profile σ^* for which the following holds

$$u_p(\sigma_p^*, \sigma_{-p}^*) = \max_{\sigma_p'} u_p(\sigma_p', \sigma_{-p}^*).$$

In other words, σ_p is the *best response* to σ_{-p} for each $p \in \mathcal{P}$. An ϵ -Nash equilibrium (in a two-player game, for example) is also defined as

$$u_p(\sigma_p^*, \sigma_{-p}^*) + \epsilon \ge \max_{\sigma_p'} u_p(\sigma_p', \sigma_{-p}^*), \quad \forall p \in \{0, 1\}.$$

We are now ready to provide an overview of CFR next; for a complete discussion, see Zinkevich et al. (2007).

CFR is an iterative algorithm that converges to a Nash equilibrium in any finite two-player zero-sum game with a theoretical convergence bound of $O\left(\frac{1}{\sqrt{T}}\right)$. At the

heart of CFR lies the concept of regret. For a strategy profile σ , instantaneous regret of playing a vs. σ at $I \in \mathcal{I}_p$ is denoted by

$$r_p(I,a) := u_p^{\sigma}(I,a) - u_p^{\sigma}(I) \tag{3}$$

In CFR, a regret matching (RM) is performed at each iteration. According to RM, at iteration T, $\sigma_p^{T+1}(I)$ is determined using regrets (3) accumulated up to time T. Formally,

$$\sigma_p^{T+1}(I) \propto R_+^T(I, a) := \left(\sum_{t=1}^T r^t(I, a)\right)_+$$
 (4)

 $R_{+}^{T}(I, a)$ is called *counterfactual regret* for infoset I action a. Under update rule (4), average strategy is then defined as follows

$$\bar{\sigma}_p^T(I)(a) \propto \sum_{t=1}^T \pi_p^{\sigma^t}(I) \, \sigma_p^t(I)(a). \tag{5}$$

The following two well-established results show that under RM (4), the average strategy (5) converges to a Nash equilibrium in zero-sum two-player games.

Theorem 1 In a zero-sum game, average strategy (5) is a 2ϵ -Nash equilibrium provided that the total regret which is defined below is less than ϵ for $p \in \{0, 1\}$.

$$R_{p}^{T} := \max_{\sigma_{p}'} \frac{1}{T} \sum_{t=1}^{T} \left(u_{p}(\sigma_{p}', \sigma_{-p}^{t}) - u_{p}(\sigma_{p}^{t}, \sigma_{-p}^{t}) \right)$$

The following theorem states that $R_p^T \to 0$ as $T \to +\infty$ under RM (4).

Theorem 2 (Theorem 3 & 4, [7]) Under RM (4), the following bound holds

$$R_p^T = \mathcal{O}\left(\frac{1}{\sqrt{T}}\right).$$

Moreover, total regret is lower bounded by counterfactual regrets defined in (4).

There are different variants of CFR where the difference is in the way it updates counterfactual regrets. For example, in CFR⁺ [5], regrets, initialized at zero, are updated according to the following rule:

$$R^{+,t}(I,a) = \left(R^{+,t-1}(I,a) + u^{\sigma^t}(I,a) - u^{\sigma^t}(I)\right)_+$$

Another example that is also used in this paper is the Discounted CFR (DCFR) [2], where prior iterations when determining both regrets and the average strategy are discounted. The update rule for DCFR is as follows:

$$R_p^t(I,a) = R_p^{t-1}(I,a) \cdot d_p^{t-1}(I,a) + r_p^t(I,a)$$
(6)

where

$$d_p^t(I,a) = \begin{cases} \frac{t^{\alpha}}{t^{\alpha} + 1} & \text{if } R_p^t(I,a) > 0\\ \frac{t^{\beta}}{t^{\beta} + 1} & \text{otherwise} \end{cases}$$
 (7)

Moreover, the average strategies are updated according to the following rule:

$$\bar{\sigma}_p^t(I)(a) \propto \left(1 - \frac{1}{t}\right)^{\gamma} \cdot \bar{\sigma}_p^{t-1}(I)(a) + \pi_p^{\sigma^t}(I)\sigma_p^t(I)(a)$$
 (8)

1.2 Pasur

Pasur is a traditional card game played with a standard 52-card deck (excluding jokers), and it supports 2 to 4 players. In this paper, we focus on the two-player variant, where the players are referred to as **Alex** and **Bob**, along with a **Dealer** who manages the game.

The game begins with four cards placed face-up on the table to form the initial pool. This pool must not contain any Jacks. If a Jack appears among the initial four cards, it is returned to the deck and replaced. If multiple Jacks are dealt, or if a replacement card is also a Jack, the dealer reshuffles and redeals.

Once the pool is valid and face-up, the dealer deals four cards to each player, starting with the player on their left (assumed to be Alex). Players then take turns beginning with Alex. On each turn, a player must play one card from their hand. The played card will either: Be added to the pool of face-up cards, or Capture one or more cards from the pool, following rules described in Table 1. If a capture is possible, the player *must* capture; they cannot simply add a card to the pool. Captured cards are retained and used to calculate each player's score at the end.

Card Type	Capture Rule
Numeric	One or more numeric cards from the pool if their total sum equals 11
Jack	All cards in the pool, except Kings and Queens (can also capture other Jacks)
Queen	A single Queen
King	A single King

Table 1: Capture rules for each card type

A **Sur** occurs when a player captures all the cards from the pool in a single move. There are two important exceptions: (1) a Sur cannot be made using a Jack, and (2) Surs are not permitted during the final round of play. Table 2 outlines Pasur's scoring system, and Figure 1 provides a gameplay example.

Rule	Points
Most Clubs	7
Each Jack	1
Each Ace	1
Each Sur	5
10♦	3
2♣	2

Table 2: Pasur Scoring System

Pasur: A Step-by-Step Gameplay Snapshot

Stage	Alex	Bob	Pool	Lay	Pick	Acl	Bel	Apt	Bpt Asr	Bsr	ΙΔ	L	CL
0,0,0	4 & 4♦ 7♦ Q &	3♦ 3♥ 5♣ ₭♠	$A \triangleq A \triangleq 9 \lozenge K \lozenge$	40	I ICK	0	0	0	0 0	0	0	0	CL
0_0_0	4♣ 7♦ 0♣	3♦ 3♥ 5♣ ₭♠	A♣ A♠ 4♦ 9♦ K♦	K.	<i>K</i> ◊	1 0	0	0	0 0	0	0	В	-
0_1_0	4♣ 7♦ ₽♣	3♦ 3♥ 5♣	A\$ A\$ 4♦ 9♦	Q.	n _V	0	0	0	0 0	0	0	В	_
0.1.1	4♣ 7♦	3♦ 3♥ 5♣	A♣ A♠ 4♦ 9♦ Q♣	5.	A♣ A♠ 4♦	0	2	0	2 0	0	0	В	-
0.2.0	4♣ 7♦	30 3♥	9◊ 0♣	44	710 710 V	0	2	0	2 0	0	0	В	-
0.2.1	7♦	3♦ 3♥	4♣ 9♢ ⊘♣	3◊		0	2	0	2 0	0	0	В	-
0.3.0	7♦	3♡	3♦ 4♣ 9♦ ₽	7♦	4♣	1	2	0	2 0	0	0	A	-
0.3.1		3♡	3◊ 9◊ 🖽	3♡		1	2	0	2 0	0	0	A	-
1,0,0	6♣ 6♦ 9♥ J♣	6♥ 7♣ J♦ K♥	3♦ 3♥ 9♦ 🗸 🗸	J♣	3♦ 3♥ 9♦	2	2	1	0 0	0	-2	A	-
1,0,1	6♣ 6♦ 9♥	6♥ 7♣ J♦ K♥	Q å	$J\Diamond$.,,	2	2	1	0 0	0	-2	A	-
1.1.0	6♣ 6♦ 9♥	6♥ 7♣ K♥	J◊ Q♣	64		2	2	1	0 0	0	-2	A	-
1.1.1	6♦ 9♥	6♥ 7♣ K♥	6 ♣ J ♦ Q♣	$K \heartsuit$		2	2	1	0 0	0	-2	A	-
1.2.0	6♦ 9♥	6♡ 7♣	6 ♣ J♦ Q♣ K♡	6♦		2	2	1	0 0	0	-2	A	-
1.2.1	9♡	6♡ 7♣	6♣ 6♦ J♦ Q♣ K♥	7.		2	2	1	0 0	0	-2	A	-
1.3.0	9♡	6♡	6♣ 6♦ 7♣ J♦ Q♣ K♡	9♡		2	2	1	0 0	0	-2	A	-
1_3_1		6♡	6♣ 6♦ 7♣ 9♥ J♦ Q♣ K♥	6♡		2	2	1	0 0	0	-2	A	-
2_0_0	5♦ 9♣ 10♥ K♣	A♦ 6♠ 8♣ 8♠	6♣ 6♦ 6♥ 7♣ 9♥ J♦ Q♣ K♥	10♡		2	2	0	0 0	0	-1	0	-
2.0.1	5♦ 9♣ K♣	A♦ 6♠ 8♣ 8♠	6♣ 6♦ 6♥ 7♣ 9♥ 10♥ J♦ Q♣ K♥	8.		2	2	0	0 0	0	-1	0	-
2_1_0	5♦ 9♣ K♣	A♦ 6♠ 8♠	6♣ 6♦ 6♥ 7♣ 8♣ 9♥ 10♥ J♦ Q♣ K♥	Κ♣	K♡	3	2	0	0 0	0	-1	A	-
2_1_1	5♦ 9♣	A♦ 6♠ 8♠	6♣ 6♦ 6♥ 7♣ 8♣ 9♥ 10♥ J♦ Q♣	$A\Diamond$	10♡	3	2	0	1 0	0	-1	В	-
2_2_0	5♦ 9♣	6♠ 8♠	6♣ 6♦ 6♥ 7♣ 8♣ 9♥ Ј♦ Д♣	5♦	6♡	3	2	0	1 0	0	-1	A	-
2_2_1	9♣	6♠ 8♠	6♣ 6♦ 7♣ 8♣ 9♡ Ј♦ Д♣	8♠		3	2	0	1 0	0	-1	A	
2_3_0	9♣	6♠	6♣ 6♦ 7♣ 8♣ 8♠ 9♥ J♦ Q♣	9♣		3	2	0	1 0	0	-1	A	-
2,3,1		6♠	6♣ 6♦ 7♣ 8♣ 8♠ 9♣ 9♥ Ј♦ Q♣	6♠		3	2	0	1 0	0	-1	A	-
3_0_0	2♣ 3♣ J♠ Q♠	7♠ 8♦ 8♥ Q♥	6♣ 6♦ 6♠ 7♣ 8♣ 8♠ 9♣ 9♥ J♦ Q♣	2♣	9♣	5	2	2	0 0	0	-2	A	-
3_0_1	3♣ J♠ Q♠	7♠ 8♦ 8♥ Q♥	6♣ 6♦ 6♠ 7♣ 8♣ 8♠ 9♡ J♦ Q♣	8♦		5	2	2	0 0	0	-2	A	-
3_1_0	3♣ J♠ Q♠	7♠ 8♡ Q♡	6♣ 6♦ 6♠ 7♣ 8♣ 8♦ 8♦ 9♡ Ј♦ Q♣	J♠	6♣ 6♦ 6♠ 7♣ 8♣ 8♦ 8♠ 9♡ Ј♦	8	2	4	0 0	0	-2	A	-
3_1_1	3♣ Q♠	7♠ 8♡ Q♡	Q.	7♠		8	2	4	0 0	0	-2	A	-
3_2_0	3♣ Q♠	$8 \heartsuit Q \heartsuit$	7♠ Q♣	3♣		8	2	4	0 0	0	-2	A	-
3,2,1	Q.	8♥ Q♥	3♣ 7♠ Q♣	Q♡	Q \$	8	3	4	0 0	0	-2	В	-
3_3_0	Q♠	8♥	3♣ 7♠	Q♠		8	3	4	0 0	0	-2	В	-
3_3_1	4♥ 4♠ 7♥ J♥	8♥ 2♦ 5♥ 9♠ 10♠	3♣ 7♠ Q♠ 7♠ Ø♠	80	3♣	8	0	4	0 0	0	-2	В	-
4_0_0	4♦ 7♥ J♥	2♦ 5♥ 9♠ 10♠		4♥ 5♥	7.	0	0	0	0 0	0	2	A	A
4_1_0	4♠ 7♥ J♥	2♦ 5♦ 9♠ 10♠	Q♠ 5♡ Q♠	7♡		0	0	0	0 0	0	2	A	A
4_1_1	4♠ / ♥ J ♥	2♦ 9♠ 10♠	5♥ Q♠ 5♥ 7♥ Ø♠	10♠		0			0 0	0	2	A	A
4.2.0	4♠ J♡	2♦ 9♠ 10♠	5♥ 7♥ 10♠ Q♠	J♡	5♡ 7♡ 10♠	0	0	0	0 0	0	2	A	A
4.2.1	4♠ 5♥	2◊ 9♠	2	20	3∨ 1∨ 10 ⊕	0	0	1	0 0	0	2	A	A
4.3.0	4♠	9♠	2◊ ◊ ◊	4♠		0	0	1	0 0	0	2	A	A
4.3.1	4.0	9♠	2♦ 4♠ Q♠	94	2◊	0	0	1	0 0	0	2	B	A
5.0.0	A♥ 3♠ 10♣ Ø◊	2♥ 2♠ 5♠ 10♦	2♥ 4₩ Q₩ 4♠ Q♠	9 . A♡	4V	0	0	0	0 0	0	3	0	A
5.0.1	3♠ 10♣ 0◊	2♥ 2♠ 5♠ 10♦	A♡ 4♠ Ø♠	5♠		0	0	0	0 0	0	3	0	A
5.1.0	3♠ 10♣ 📿♦	2♥ 2♠ 10♦	A♥ 4♠ 5♠ O♠	10.	$A \heartsuit$	1	0	1	0 0	0	3	A	A
5.1.1	3♠ 0◊	2♥ 2♠ 10♦	4♠ 5♠ Q♠	10♦		1	0	1	0 0	0	3	A	A
5.2.0	3♠ 0◊	2♥ 2♠	4♠ 5♠ 10♦ 🗸	0◊	Q &	1	0	1	0 0	0	3	A	A
5.2.1	3♠	2♥ 2♠	4♠ 5♠ 10♦	2♠	4♠ 5♠	1	0	1	0 0	0	3	B	A
5.3.0	3♠	2♡	100	36		1	0	1	0 0	0	3	В	A
5.3.1		2♡	3♠ 10♦	2♡		1	0	1	0 0	0	3	В	A
CleanUp			- 	+		1	0	1	3 0	0	2	В	A
CleanOp						1	1 0	1 1	1 9 1 0	L U	L -2	_ D	Α

Figure 1: Columns Acl, Apt, and Asr represent the number of clubs, points, and surs collected or earned by Alex so far. Bcl, Bpt, and Bsr are defined similarly for Bob. Once, at the end of any round, Acl exceeds 7, both Acl and Bcl reset to zero, and the column CL indicates which player collected at least 7 clubs. According to Pasur rules, this player earns 7 points. Collecting more than 7 clubs yields no additional points unless the card is also a point card (i.e., e.g., A& or 2\Lambda). The column Δ shows the cumulative point difference up to the end of the previous round. Δ updates at the end of each round to reflect the points earned in that round. Finally, in the CleanUp phase, the player who made the last pick (as shown in column L) collects all remaining cards from the pool. If any point cards are present, the corresponding point columns will be updated. If there are club cards in the CleanUp phase and neither player has yet reached 7 clubs, then the remaining clubs in the pool determine who earns the 7-club bonus. In such situations, the identity of the last player to pick becomes critical.

In the displayed game above, Alex earns the 7-club bonus. Bob gains 3 points from collecting $10\diamondsuit$, but he is trailing by 3 points from the rounds preceding the last. Additionally, Alex earns 1 point in the final round from capturing the $A\heartsuit$ card. This results in a final score with Alex leading by 8 points. See Table 2 for the Pasur scoring system.

2 PyTorch-Based Framework

In this section, we present our computational framework for implementing for simulating Pasur using PyTorch. The game consists of 6 rounds, and in each round, both players take 4 turns, giving rise to a game tree of depth 48. We begin by describing how a set of cards is represented as a PyTorch tensor. As illustrated in Figure 2, each card is mapped to a unique tensor index according to a fixed, natural order. The interpretation of the tensor values at these positions varies depending on the specific tensor in which they appear: it may indicate card ownership (e.g., who holds the card) or an action involving that card (e.g., laid or picked), depending on whether the tensor encodes game state, actions, or other game-related structures. This indexing convention serves as the foundation for constructing all tensors listed in Table 4.

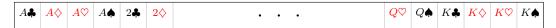


Figure 2: Mapping Cards to Indices

To manage memory efficiently during game tree generation, we maintain two boolean tensors that track card availability throughout the game. Let m denote the number of *in-play cards*—those currently in play, either held by a player or present in the pool. For instance, in the first round, m = 12, since each player is dealt four cards and four cards are placed in the pool. At the end of each round, we update the set of in-play cards: we remove any cards that have been picked across all nodes and add new cards that are about to be dealt.

This information is captured using the t_inp tensor. This binary tensor marks which cards are currently involved in the game—either held by players or present in the pool—and serves as the basis for constructing and updating all relevant tensors during game tree generation. It is emphasized that as a result of this, the shapes of certain tensors—particularly those that represent actions or action history, such as t_act and t_gme—may vary across rounds to reflect the current number of in-play cards. To illustrate this point, consider the initial configuration of the game shown in Table 3, with the corresponding t_inp tensor depicted in Figure 3.

Table 3: Initial setup for a single game instance

Alex	4 ♣	$4\diamondsuit$	7\$	$Q \clubsuit$
\mathbf{Bob}	$3\diamondsuit$	$3 \heartsuit$	5 ♣	$K \spadesuit$
Pool	$A \clubsuit$	$A \spadesuit$	$9\diamondsuit$	$K\diamondsuit$



Figure 3: t_inp tensor at the beginning of the game for initial setup in Table 3

We next provide an overview how the game tree is generated and recorded using tensor operations. During the tree construction process, we distinguish between

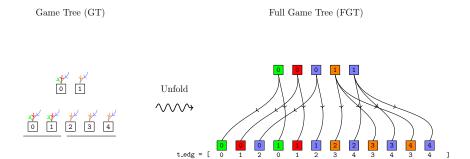


Figure 4: Unfolding Process

the card state—including the cards held by Alex, the cards held by Bob, and the cards in the pool—and the score information, which is updated independently. A given card state may correspond to multiple incoming edges, each representing a different score inherited from earlier rounds. Figure 5 illustrates this structural design. Alongside the Game Tree (GT) illustrated in Figure 5, we construct a Full Game Tree (FGT) via an unfolding process (Figure 4), which systematically expands the tree by combining each card state with all compatible incoming scores.

To ensure memory efficiency, the only parameters stored for FGT are the strategy values at each node and the edges linking nodes between successive layers.

Thus, each node in FGT is represented as a pair: a GT node and its corresponding incoming score. We explicitly maintain the edge structure between FGT nodes, which is crucial for updating strategies during the CFR iterations. Figure 4 provides a visual representation of the unfolding process. Further details on this mechanism and the edge-tracking procedure are discussed in the subsections that follow.

This section is organized as follows. We begin by describing the mask and padding tensors used during game tree generation in Subsection 2.1. These tensors help track the indices of cards within the current tensor as the size of these tensors may vary from round to round due to the fact that the set of in-play cards changes dynamically. Next, in Subsection 2.2, we describe the construction of the Game Tensors. These tensors encode the state and action history. Subsection 2.3 explains how the Action Tensors are built and how they are used to update the Game Tensors. Once the construction of the Action Tensors is understood, we proceed to explain the construction of the Compressed Tensor in Subsection 2.4, where all game information up to the current point is encoded in a tensor of shape [58]. Next, Subsection 2.5 explains the two types of score tensors used: the Running-Score Tensor, which accumulates scores across a single round, and the score tensors that are passed along the edges of GT, containing scores inherited from previous rounds. Then, in Subsection 2.6, we detail how FGT Tensors are updated within each round; it also introduces the construction of Edge Tensors. Following that, Subsection 2.7 describes the Between-Hand updates, including how the Score Tensor and FGT tensors are updated at the end of each round, along with the Linkage Tensor. Finally, Subsection 2.8 explains how Infoset Tensors are constructed.

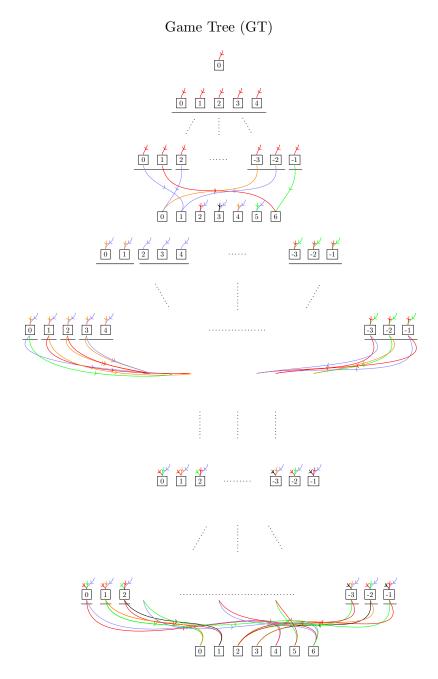


Figure 5: We distinguish between the *card state* and the *score information*, which are updated independently. A given card state may correspond to multiple incoming edges, each representing a different score inherited from earlier rounds. Underlines indicate the number of available actions for each parent node.

Before proceeding to the next section, we summarize the key components of our framework in Table 4. Padding-related tensors are described separately in Table 5.

Table 4: Summary of Tensors Used in Our Framework

Component	Tensor	Shape	Type	Update	Description
Game	t_gme	[M,3,m]	int8	Per turn	Encodes state and action history per node. Each slice represents a singleton node in the tree layer.
In-Play Cards	$t_{-}inp$	[52]	int8	Per round	Boolean indicator for whether each of the 52 cards is still in play (held or in pool).
Dealt Cards	t_dlt	[52]	int8	Per round	Boolean indicator marking cards that have been dealt in previous rounds.
Full Game	t_fgm	[Q, 2]	int32	Per turn/round	Each row [g, s] in t_fgm indicates that GT's node t_gme[g,:] inherits the score with ID s from t_scr. Here, Q denotes FGT's current layer's number of nodes.
Scores	t_scr	[Q, 4]	int8	Per turn/round	Unique score in form (Alex Clubs, Bob Clubs, Point Difference, 7-Clubs Bonus). Scaled each turn using ⊗t_brf. See Section 2.6 for in-between hands updates.
Runnsing Scores	t_rus	[M,7]	int8	Per turn	Unique score in form (Alex Club, Bob Club, Last Picker, Alex Points, Alex Sur, Bob Points, Bob Sur).
Action	t_act	[M',2,m]	int8	Per turn	Action representation per node. [0,:] encodes the lay card; [1,:] encodes picked cards. Here, M' denotes the number of nodes in GT's next layer.
Branch Factor	t_brf	[M]	int8	Per turn	Number of valid actions available from each node; used to replicate game states before applying actions. Indicated using underlines in Figure 5.
Linkage	t_lnk	[Q]	int32	Per round	Connects FGT nodes between consecutive hands to identify how scores and states map across hands.
Edge	t_edg	[Q']	int32	Per turn	Records edges between FGT nodes to track the structure of the overall graph. Here, Q' denotes the number of nodes in the FGT's next layer.
Strategy	t_sgm	[Q]	float32	Per turn	Stores strategy values (e.g., probabilities) associated with each FGT's node.
Compressed Game	t_cmp	[M, m]	int8	Per turn	Stores the entire game information up to the current turn in a compressed format.
Infoset	t_inf	[Q,58]	int8	Per turn	Encodes information available to player whose turn it is. t_inf hides information that is not observable by the acting player. Includes metadata such as round index, turn counter, and cumulative score up to the previous round.

2.1 Mask and Padding Tensors

We now describe how masks and padding tensors are constructed from the in-play card tensor t_inp, which has shape [M, 52] and indicates which cards are active during a round.

Table 5: Mask and Padding Variables

Variable	Description
t_inn, t_inq, t_ink, t_inj, t_inc, t_ins	Masks for Numerical, Queen, King, Jack, Club, and Point cards resp.
i_pdn, i_pdj, i_pdq, i_pdk	Padding sizes for Numerical, Jack, Queen, and King actions resp.
t_pdq, t_pdk	Permutations to restore Queen and King actions to original order, resp.

Table 6: Index Sets for Card Categories and Scoring

Index Set	Description
<pre>l_n = range(40) l_j = [40, 41, 42, 43] l_q = [44, 45, 46, 47] l_k = [48, 49, 50, 51]</pre>	Numerical cards (2 to 10 of all suits including Aces). Jacks. Queens. Kings.
<pre>1.c = range(0, 52, 4) 1.p = [0,1,2,3,4,37,40,41,42,43] 1.s = [1,1,1,1,2,3,1,1,1,1]</pre>	Clubs (every 4th card). Scoring cards: all Aces, 2♣, 10♦, all Jacks. Scores corresponding to entries in 1_p.

To compute masks in Table 5, we use the index sets from Table 6, which are computed as follows:

Here the helper function f is defined below:

f = lambda lm: tensor([id in lm for id,card in enumerate(t_inp) if card])

We compute the counts of each category:

We also define intermediate sums:

Using these, we define:

```
i_pdn, i_pdj, i_pdk, i_pdq = i_jqk, i_kq, i_njq, i_njk
```

And the corresponding padding permutations:

```
t_pdk = hstack((arange(i_k, i_njqk), arange(i_k)))
t_pdq = hstack((arange(i_q, i_njq), arange(i_q), arange(i_njq, i_njqk)))
```

2.2 Game Tensor

Each row in the game tree (Figure 5) is represented using an [M,3,m] GT tensor t_gme, where M corresponds to the number of nodes in the current GT's layer. The associated [3,m] tensor is constructed for each node: Each slice t_gme[g,:,:] encodes a single game state. The first row of the tensor, t_gme[g,0,:], represents the current card holdings and pool status. To encode the game state numerically, we assign integer identifiers to the entities involved, as shown in Table 7.

Table 7: State Encoding in t_gme[g,0,:]

Element	Encoding
Alex	1
Bob	2
Pool	3

The remaining two rows of t_gme, namely t_gme[g,1,:] and t_gme[g,2,:], record the action histories of Alex and Bob, resp. We describe the construction of t_gme[g,1,:] in detail below; the construction of t_gme[g,2,:] is analogous.

Each round consists of four turns, meaning that Alex plays a card four times per round. During each turn i_trn = i, for i = 0, 1, 2, 3, he may or may not collect cards from the pool.

Suppose Alex plays the card A° on his first turn and collects 10° . We update $t_{gme}[g, 1,:]$ by recording the value 1 at the position corresponding to A° , and adding the value 10 at the position corresponding to 10° . If Alex collects multiple cards from the pool on his first turn, the value 10 is added to all corresponding positions in $t_{gme}[g, 1,:]$ for each collected card. For subsequent turns, similar updates are performed, except we use the value pairs (2,20), (3,30), and (4,40) instead of (1,10) for the second, third, and fourth turns, respectively.

Importantly, t_gme[g,0,:] is updated after each move to reflect the current state of the game. For cards that are played but not collected, the corresponding position in t_gme[g,0,:] is set to 3. If a played card is used to collect one or more cards from the pool, then the corresponding positions are updated as follows: hand cards that were played or picked change from 1 to 0, and pool cards that were collected change from 3 to 0. See CodeSnippet 1.

2.3 Actions

At each turn, we first compute two key tensors: the Branch Factor Tensor t_brf and the Action Tensor t_act: t_brf is a tensor of length M, where M is the number of nodes in the current round. Each entry t_brf[g] records the number of valid actions available from node g. Correspondingly, t_act is a binary tensor of shape [M',2,m], where m is the number of in-play cards. Here, M'=t_brf.sum() is the total number of resulting nodes in the next round, created by enumerating all valid actions from the current nodes. Each slice t_act[j,:,:] encodes a single action, consisting of two rows as described in Table 8.

Table 8: Structure of the Action Tensor t_act

Tensor Slice	Description
t_act[j, 0, :]	Encodes the <i>lay card</i> . Contains exactly one 1 at the index of the played card; all other entries are 0.
t_act[j, 1, :]	Encodes the $picked\ cards$ from the pool. May contain zero or more 1s depending on the number of picked cards.

To update the game state tensor t_gme for the next round, we first replicate each current node g according to its corresponding $t_brf[g]$ count, effectively expanding t_gme to match the total number of action slices M'. This is done using the repeat_interleave operator, denoted by the Kronecker product symbol: \otimes .

$$t_gme \leftarrow t_gme \otimes t_brf$$

This expansion ensures that each valid action is paired with its own copy of the corresponding game state. Then, each slice of t_act is applied to the corresponding replicated game state to produce the updated states. Finally, we apply the encoded actions by updating t_gme using t_act. See CodeSnippet 1.

CodeSnippet 1 ApplyActions

```
1: Input t_gme, t_act, i_ply, i_trn
# t_act.shape[0] = t_gme.shape[0] after expansion t_gme \( \times \) t_gme \( \times \) t_brf
2: t_mpk \( \times \) any(t_act[:,1,:], dim=1)
# Whether a pick action occurs
3: t_gme[t_mpk,0,:]+=(2-i_ply)*t_act[t_mpk,0,:]
# Add lay card to pool (only if no pick)
4: t_gme[t_mpk,0,:]-=(1+i_ply)*t_act[t_mpk,0,:]
# Remove lay card from player's hand
5: t_gme[t_mpk,0,:]-=3*t_act[t_mpk,1,:]
# Remove picked cards from the pool
6: t_gme[:,i_ply+1,:]+=(i_trn+1)*t_act[:,0,:]+10*(i_trn+1)*t_act[:,1,:]
# Update player record: lay (weighted by i_trn+1) + pick (weighted by 10 \times i_trn+1)
```

We now present how the Action Tensor t_act is constructed using the GT tensor t_gme. There are four types of actions: Numerical, Jack, King, and Queen. The construction process is explained below. To derive actions from a given t_gme tensor, we first construct an int8 tensor of shape [2, 52] denoted as t_2x52, along

with various views such as t_2x40 , t_2x44 , and two t_2x4 tensors corresponding to different action types. The construction of t_2x52 is explained in CodeSnippet 2. Once t_2x52 is obtained, we define the inputs to each action operator as:

CodeSnippet 2 t_2x52

```
1: Input t_gme

2: t_2x52 ← zeros((t_gme.shape[0],2,t_gme.shape[2]))

3: t_2x52[:,0,:][t_gme[:,0,:]==i_ply+1]←1

4: t_2x52[:,1,:][t_gme[:,0,:]==3]←1
```

```
t_2x52[:,:,t_msk] for t_msk in [t_inn, t_inn+t_inj, t_ink, t_inq]
```

These serve as inputs to the Numerical, Jack, King, and Queen action routines, respectively. For memory efficiency, we first apply unique to these tensors and pass the result to n_act, j_act, k_act, and q_act to compute the action and branch factor tensors. We next pass each resulting action and branch tensor pair t_act, t_brft to CodeSnippet 3 to map them back to the full tensor.

CodeSnippet 3 Mapping Back Actions from Unique Tensor to Full Tensor

```
1: Input t, f_act # t: input tensor, f_act: function to find actions (e.g., numerical, jack, etc.)
 2: tu, t_inx ← unique(t, sorted=Fasle, return_inverse=True)
 3: tu_act, tu_brf ← f_act(tu)
 4: t_brf ← tu_brf[t_inx]
 5: t_act ← tu_act[inverseunique(tu_brf,t_inx)]
 6: return t_brf, t_act
 7: function INVERSEUNIQUE(t_cnt,t_inx) # Ex: t_cnt = [2,3], t_inx = [1,0,0]
        t_cms \leftarrow zeros(t_cnt.shape[0]+1, dtype=int32) # = [0,2,5]
 8:
 9:
        t_cms[1:] \leftarrow t_cnt.cumsum(0)
       t_bgn \leftarrow t_cms[t_inx] \# = [2,0,0]
10:
       t_{len} \leftarrow t_{cnt}[t_{inx}] \# = [3,2,2]
11:
       t_{lns} \leftarrow t_{len.cumsum}(0) \# = [3,5,7]
12:
        t_{ofs} \leftarrow arange(t_{lns}[-1]) - (t_{lns} - t_{len}) \otimes t_{len}
13:
    \# \text{ arange(t_lns[-1])=[0,1,2,3,4,5,6], t_lns-t_len=[0,3,5]}
    # (t_lns - t_len)\otimest_len = [0,0,0,3,3,5,5], t_ofs = [0,1,2,0,1,0,1]
14:
        return t_bgn\otimest_len + t_ofs \# = [2,2,2,0,0,0,0] + [0,1,2,0,1,0,1] = [2,3,4,0,1,0,1]
15: end function
```

We denote the resulting action tensors as t_pck, t_lay, t_kng, t_jck, t_qun and the corresponding branch factor tensors as c_pck, c_lay, c_kng, c_jck, c_qun. It is emphasized that n_act produces two pairs of action and branch factor tensors: Pick and Lay pairs. Pick actions correspond to cases where at least one card (along with the card in hand) is picked from the pool, while Lay actions correspond to cases where no card is picked and only one card is laid down and added to the pool.

We pad these tensors to match the original shape of tensor t_2x52 as follows:

```
t_pck = pad(t_pck, (0, i_pdn))
t_lay = pad(t_lay, (0, i_pdn))
t_kng = pad(t_kng, (0, i_pdk))[:,:,t_pdk]
t_qun = pad(t_qun, (0, i_pdq))[:,:,t_pdq]
t_jck = pad(t_jck, (0, i_pdj))
```

The branch factor is also easily calculated as below

```
t_brf = sum(stack([c_pck, c_lay, c_kng, c_qun, c_jck]), dim=0)
```

We perform one final step to construct the action tensor t_act. This step ensures that all actions corresponding to each row of the game tensor are grouped together. To achieve this, we repeat each row index of the game tensor according to its corresponding branch factor, and then use the sorted indices to reorder the concatenated action tensors.

```
_, t_inx = sort(cat([arange(M)\otimest for t in [c_pck,c_lay,c_kng,c_qun,c_jck]]))
```

Once t_inx is obtained, the final action tensor is constructed by concatenating all action components and reordering them using t_inx:

```
t_act = cat([t_pck, t_lay, t_kng, t_qun, t_jck])[t_inx]
```

2.3.1 Numerical Actions

In this section, we explain how Numerical Actions are constructed. Recall that the input tensor to n_act is given by t_2x40 = t_2x52[:,:,t_inn].

We begin by identifying all possible combinations of numerical cards such that the sum of each subset equals 11. This is a classical instance of the *Subset Sum Problem* (SSP), which we solve using dynamic programming. The solutions are stored in a tensor t_40x2764 of shape [40, 2764], where each row corresponds to one of the 40 numerical cards, and each column represents a valid subset whose sum equals 11. We also define an auxiliary tensor t_tpl as in Table 9.

Table 9: Tuple Tensor t_tpl of shape [2, 2764]

Row	Description
t_tpl[0,:] t_tpl[1,:]	All entries are 1, representing a fixed lay card for each action. Stores the number of cards from the pool that are involved in each action.

Since we mask only for in-play cards, we need to exclude those that are not in-play. To this end, we apply the mask t_inp[:40] to t_40x2764 by computing t_40x2764[:, t_inp[:40]], and pass the resulting tensor to n_act. We still denote t_40x2764 as the masked tensor for convenience. Moreover, denote by t_2764x40 the transpose of t_40x2764. We now describe how tensors t_pck and t_lay are constructed. The process begins with t_pck, from which t_lay is subsequently derived. Consider the matrix product

```
matmul(t_2x40, t_40x2764)
```

which results in a tensor of shape [M,2,2764], where M is the number of rows in t_2x40. This tensor evaluates how each input pair of player hand and pool (i.e., each row of t_2x40) overlaps with the precomputed subset-sum solutions in t_40x2764. Notice masking out t_40x2764 does not affect the outcome of the matrix multiplication, as masked entries are 0 and thus do not contribute to the result.

A pair of player hand and pool (i.e., row i of t_2x40) is said to have the action j available if and only if the count of matching cards exactly matches the template t_tpl[:, j]. The following code yields all indices [i, j] such that action j is valid for row i of t_2x40.

```
t_{inx} = nonzero(((t_{tpl} - matmul(t_{2x40}, t_{40x2764})) == 0).all(dim=1))
```

We use the index tensor t_inx to construct the pick action tensor t_pck. Computing the corresponding t_brf is straightforward from t_inx; it is computed as follows:

```
c_pck = t_inx[:,0].bincount(minlength=M)
```

Now that we have the number of actions available for each row and also the indices of the corresponding actions in t_inx, we could obtain t_pck as follows: We repeat each row of t_2x40 based on the number of available actions for that row. Simultaneously, we repeat each available action twice along dim=1. Then, we apply the logical_and operator to identify matching cards. The following performs this computation:

```
t_pck = logical_and(t_2x40 \otimes c_pck, t_2764x40[t_inx[:,1]].unsqueeze(1) \otimes_1 2)
```

Here each row of t_2764x40[t_inx[:,1]] corresponds to a valid available action.

We are now ready to construct the Lay Action tensor t_lay. The main idea is to identify which cards in the player's hand have not been used in any Pick Action. To achieve this, we first build a tensor t_hnd that records how many times each card in the hand has been selected for a Pick Action. This is accomplished using the scatter_add_ operation. The index tensor used for this purpose has the same shape as t_pck[:,0,:], and rows corresponding to the same row in t_2x40 are grouped together through this index tensor. Once t_hnd is constructed, we subtract it from the player's original hand tensor t_2x40[:,0,:] and apply relu to isolate the remaining cards that were not picked. The result is a binary tensor indicating candidate cards for Lay Actions. The remainder of the construction is straightforward and presented in CodeSnippet 4.

CodeSnippet 4 Constructing Lay Action Tensor from Pick Tensor

```
1: m_pck \leftarrow c_pck > 0
 2: t_cnt \leftarrow c_pck[m_pck]
 3: i_cnt ← t_cnt.shape[0]
4: # Construct hand tensor by summing picked cards
 5: t_hnd ← zeros((i_cnt, m))
 6: t_{inx} \leftarrow (arange(i_{cnt}) \otimes t_{cnt}).view(-1,1).expand(-1, m)
 7: t_src \leftarrow t_pck[:,0,:]
 8: t_hnd.scatter_add_(0, t_inx, t_src)
9: # Remove picked cards from hand to construct lay
10: t_cln \leftarrow t_2x40[:,0,:].clone()
11: t_cln[m_pck,:] \leftarrow relu(t_2x40[m_pck,0,:]-t_hnd)
12: # Find positions to lay the remaining card
13: t_{inx} \leftarrow nonzero(t_{cln} == 1)
14: c_{\text{lay}} \leftarrow \text{bincount}(t_{\text{inx}}[:,0], \text{minlength=M})
15: t_{\text{lay}} \leftarrow zeros((t_{\text{inx.shape}}[0], 2, m))
16: t_{lay}[arange(t_{lay}.shape[0]), 0, t_{inx}[:,1]] \leftarrow 1
```

2.3.2 Jack Actions

As discussed earlier, t_2x44 = t_2x52[:,:,t_inn+t_inj] serves as the input tensor to the j_act function. The first step is to identify all rows in t_2x44 that contain Jack cards. This is accomplished by:

```
t_{inx} \leftarrow nonzero(t_{2x44}[:, 0, i_{pdn}:])
```

Recall from Table 5 that i_pdn denotes the number of numerical cards among the current in-play cards. The corresponding branch factor tensor is obtained via:

```
c_jck \( \tau_inx[:, 0].bincount(minlength=M)
```

To construct the Jack Action tensor t_jck, we first let i_cnt = t_inx.shape[0]. Since each Jack card corresponds to exactly one action, the tensor t_jck is initialized with shape [i_cnt, 2, m]. This tensor is then populated as follows:

```
 \begin{array}{l} t\_rng \leftarrow arange(i\_cnt) \\ t\_jck[t\_rng, 0, i\_pdn + t\_inx[:,1]] \leftarrow 1 \\ t\_jck[t\_rng, 1, :] \leftarrow t\_2x44[:,1,:] \otimes c\_jck \end{array}
```

2.3.3 King Actions

In this section, we describe how King Action is constructed; the construction of Queen Action follows similarly. Recall that the input to k_{act} is given by $t_{2x4} = t_{2x52}[:, :, t_{ink}]$. Since we apply unique before passing the tensor to k_{act} (as explained earlier), the input tensor t_{2x4} has a limited number of unique possibilities. Specifically, the number of rows in t_{2x4} cannot exceed 3**4 = 81. Each

row of t_2x4 is first converted into a string of length 4. To generate this string representation, we first apply the transformation

```
t_2x4[:, 1, :][t_2x4[:, 1, :] == 1] = 2,
```

and then compute $t_2x4.sum(dim=1)$, which is subsequently converted into a string key. For example, '0201' indicates that the player holds a $K\spadesuit$, while the pool contains a $K\diamondsuit$. This key is then used to index into the dictionary to retrieve the corresponding action tensor. Finally, we use this key to look up the corresponding action tensor in our dictionary. CodeSnippet 5 summarizes this discussion. Details regarding the lookup table are omitted here; please refer to the GitHub code repository for full implementation details.

CodeSnippet 5 Constructing King Action Tensor

```
1: t_2x4[:, 1, :][t_2x4[:, 1, :] == 1] ← 2

2: M0 ← t_2x4.shape[0]

3: Build lookup_tbl using t_2x4.sum(dim=1).

4: c_k ← tensor([lookup_tbl[i].shape[0] for i in range(M0)])

5: t_k ← cat([lookup_tbl[i] for i in range(M0)], dim=0)
```

2.4 Compressed Game Tensor

In this subsection, we represent a game tensor t_gme of shape [M, 3, m] using a compressed form t_cmp of shape [M, m]. This compressed tensor is later used to build the Infoset representation in Section 2.8. During GT construction, all resulting t_cmp tensors are stored, and it becomes straightforward to mask information not observable by the acting player through simple masking operations. Next, we describe how t_cmp is constructed and explain why this construction uniquely encodes a GT layer, given the current In-Play tensor t_inp. See CodeSnippet 6.

CodeSnippet 6 Compressed Game Tensor

```
1: Input: t_gme
2: t_cmp \( \times \) t_gme[:,1,:] - t_gme[:,2,:]
3: t_lpm \( \times \) logical_and(t_gme[:,0,:] == 0, (t_cmp != 0) & (t_cmp.abs() < 5))
4: t_cmp[t_lpm] \( \times \) 110 + t_cmp[t_lpm]
5: t_cmp[logical_and(t_gme[:,0,:] == 3, t_cmp == 0)] \( \times \) 110
6: t_cmp[logical_and(t_gme[:,0,:] == 1, t_cmp == 0)] \( \times \) 100
7: t_cmp[logical_and(t_gme[:,0,:] == 2, t_cmp == 0)] \( \times \) 105
```

In Table 11, we summarize all possible values that can appear in the compressed tensor t_cmp. Each card can have up to two legs in a round. The first leg corresponds to when the card is laid into the pool, and the second leg corresponds to when it is picked from the pool. A card may have only one leg in the current layer of the game tensor—this occurs when a player lays the card into the pool, but it has not yet been picked by any player. Alternatively, a card may have no legs in the current round; this happens when the card was already in the pool at the start of the round

or is still held by one of the players. By design of the game tensor t_gme, we can characterize these situations precisely:

Table 10: Leg Status Conditions for Cards

No Legs	One Leg	Both Legs in Same Turn
t_cmp==0	t_gme[:,0,:]==3 & t_cmp!=0	t_gme[:,0,:]==0 & (t_cmp != 0) & (t_cmp.abs() < 5)

Table 11: Compressed Game Tensor Values in t_cmp

Value	First Leg	Second Leg	Description
100		_	Held by Alex
105	_	_	Held by Bob
110	_	_	Was already in the pool
111,112,113,114	Alex laid at i_trn=0:3	Alex picked at same turn	Both legs in same turn by Alex
109,108,107,106	Bob laid at i_trn=0:3	Bob picked at same turn	Both legs in same turn by Bob
1,2,3,4	Alex laid at i_trn=0:3		Not yet picked
-1,-2,-3,-4	Bob laid at i_trn=0:3	_	Not yet picked
-9,-19,-29,-39 -18,-28,-38 -27,-37 21,31,41 32,42 43	Alex laid at i_trn=0 Alex laid at i_trn=1 Alex laid at i_trn=2 Alex laid at i_trn=0 Alex laid at i_trn=1 Alex laid at i_trn=1	Bob picked at i_trn=0:3 Bob picked at i_trn=1:3 Bob picked at i_trn=2:3 Alex picked at i_trn=1:3 Alex picked at i_trn=2:3 Alex picked at i_trn=3	
19,29,39 28,38 37 -21,-31,-41 -32,-42 -43	Bob laid at i_trn=0 Bob laid at i_trn=1 Bob laid at i_trn=2 Bob laid at i_trn=0 Bob laid at i_trn=1 Bob laid at i_trn=1	Alex picked at i_trn=1:3 Alex picked at i_trn=2:3 Alex picked at i_trn=3 Bob picked at i_trn=1:3 Bob picked at i_trn=2:3 Bob picked at i_trn=3	

2.5 Score Tensors

There are two types of score tensors: those that store the score accumulated within a single round, called the running-score tensor t_rus, and those that are passed along edges in GT, referred to as the score tensor t_scr. The tensor t_rus is initialized to zero at the beginning of each round and is updated after every turn. At the end of the round, the final value of t_rus is used to update t_scr. Tables 12 and 13 outline the meaning of each index in the score tensors t_scr and t_rus, respectively. Note that the running-score tensor t_rus includes additional components relevant to a single round.

Table 12: Column definitions for the score tensor

Alex Club	Bob Club	Point Difference	7-Clubs Bonus
0	1	2	3

Table 13: Column definitions for the running-score tensor

Alex Club	Bob Club	Last Picker	Alex Points	Alex Sur	Bob Points	Bob Sur
0	1	2	3	4	5	6

We need to clarify an important point about the score tensor t_scr. After each round, once the number of Clubs collected by either Alex or Bob reaches 7, we update the last column—the 7-Clubs Bonus—to reflect that one of the players has achieved the bonus. Specifically, the value becomes 1 if Alex reaches 7 Clubs, or 2 if Bob does. At the same time, the counts in the first two columns, which track Clubs for Alex and Bob respectively, are reset to 0.

For example, the score vector [3, 8, 2, 0] is not a valid state; it will be converted to [0, 0, 2, 2], indicating that Bob has earned the 7-Clubs bonus. At this point, accumulating additional Clubs is irrelevant to the 7-Clubs bonus and is therefore not tracked. The primary advantage of this design choice is that it reduces the number of possible edges (and hence the size of the FGT), resulting in significant savings in both computation and memory.

We omit the procedure for updating the running-score tensor and refer the reader to the Github repository.

2.6 In-Hand Updates

In this section, we explain how in-hand updates are performed. A key operation required throughout is a generalized version of torch.repeat_interleave, which we refer to as **RepeatBlocks**. Unlike torch.repeat_interleave, which repeats individual elements, RepeatBlocks operates on entire contiguous blocks of elements and repeats them as a whole. This operation is detailed in Appendix 5.

We now explain how FGT is updated within each round. Two tensors are updated during this process: the FGT tensor t_fgm and the Edge tensor t_edg, which captures the connections between nodes across successive layers of FGT.

The FGT tensor t_fgm is used to track which scores accumulated from previous rounds (stored in t_scr) are linked to each node of the GT tensor t_gme. A row entry [g, s] in t_fgm indicates that node t_gme[g] inherits the score t_scr[s] from a previous round. See Figure 6 for an example consistent with the setting illustrated on the left-hand side of Figure 4.

Figure 4 illustrates how t_edg is constructed. On the left-hand side, we show two parent nodes—one with 2 child nodes and 3 inherited scores, and the other with 3 child nodes and 2 inherited scores. The right-hand side of the figure illustrates the corresponding structure within FGT. Here, colors denote inherited scores from the previous round, and numbers represent the row indices from the current GT tensor t_gme. An edge is drawn when the score colors match and the nodes are connected in the folded GT. In this example, the tensor

$$t_{edg} = [0,1,2,0,1,2,3,4,3,4,3,4]$$

records the parent indices in FGT. The counts of inherited scores and available

$$t_scr = \begin{bmatrix} \bullet \\ \bullet \\ \end{bmatrix}, \qquad t_fgm = \begin{bmatrix} 0 & \bullet \\ 0 & \bullet \\ 1 & \bullet \\ 1 & \bullet \end{bmatrix}$$

Figure 6: An example illustrating how the FGT tensor t_fgm associates nodes in the GT with entries in the Score Tensor t_scr. Colors are used to indicate rows of t_scr, consistent with Figure 5. Each row of t_scr is represented by a tensor of size 4, as described in Table 12.

actions per parent are given by c_scr = [3,2] and t_brf = [2,3], respectively. This structure can be generated compactly by the RepeatBlocks operator as follows:

$$t_edg \leftarrow arange(t_fgm.shape[0]) \otimes_{c_scr} t_brf.$$

We will next explain how the FGT tensor t_fgm is updated. Figure 7 shows the t_fgm tensors before and after the update, corresponding to the setting of Figure 4. The update to t_fgm is performed in two phases: first, we update t_fgm[:,1]; then, we update t_gme and c_scr before proceeding to update t_fgm[:,0]. We have

$$t_{fgm}[:,1] \leftarrow \begin{bmatrix} \blacksquare & \blacksquare & \blacksquare \end{bmatrix} \otimes_{[3,2]} [2,3]$$

where the first tensor on the right-hand side is $t_fgm[:,1]$. The first three colors are repeated twice on the right-hand side of Figure 7 because $t_brf[0] = 2$, and the last two are repeated three times because $t_brf[1] = 3$. Therefore

$$t_fgm[:,1] \leftarrow t_fgm[:,1] \otimes_{c \ scr} t_brf$$

Furthermore,

$$t_fgm[:,0] \leftarrow [0,1,2,3,4] \otimes [3,3,2,2,2]$$

In words, each node in GT's second layer in the left-hand side of Figure 4 is repeated as many times as the number of scores it inherited from the previous round. Namely,

$$t_{gm}[:,0] \leftarrow arange(t_{gme.shape}[0]) \otimes c_{scr}$$

Both t_gme and c_scr are updated before the equation above.

2.7 Between-Hand Updates

In this section, we introduce the processing framework used at the beginning of each hand. Figure 8 illustrates this process. By the end of each hand, we obtain a set of GT nodes, each associated with one or more inherited scores from previous rounds. Our goal is to construct the root-level nodes of GT's next round, along with their inherited scores. To begin, we identify the unique game states and running-score

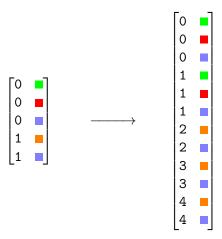


Figure 7: An illustration of how t_fgm is updated.

tensors at the terminal level of the current round. This is achieved via the following operation:

```
t_gme, t_gnk = unique(t_gme, dim=0, sorted=False, return_inverse=True)
t_rus, t_rnk = unique(t_rus, dim=0, sorted=False, return_inverse=True)
```

We first update the second column of FGT tensor t_fgm, namely t_fgm[:,1], which encodes the inherited scores. To propagate scores correctly, we take the score components from the previous round, stored in t_fgm[:,1], and add the scores earned during the current hand, recorded in t_rus. To this end, we represent each player's total score—comprising both the inherited and running components—as follows:

$$t_prs \leftarrow cat([t_fgm[:,1], t_rnk[t_fgm[:,0]]], dim=1)$$

Concatenate these two components to identify the unique score combinations:

```
t_prs, t_pid \( \to \text{unique(t_prs, dim=0, sorted = False, return_inverse=True)} \)
```

Each unique pair in t_prs represents a total score passed to the next round, and is computed by summing the individual components:

$$t_scr \leftarrow t_scr[t_prs[:,0]]+t_rus[t_prs[:,1]]$$

We next eliminate duplicate score values using another call to unique:

```
t_scr, t_fid ← unique(t_scr, dim=0, soretd=False, return_inverse=True)
```

This gives us enough ingredients to update t_fgm[:,1] as follows:

$$t_fgm[:,1] \leftarrow t_fid[t_pid]$$

Now we update the first column of the FGT t_fgm[:,0] as follows:

$$t_fgm[:,0] \leftarrow t_gnk[t_fgm[:,0]]$$

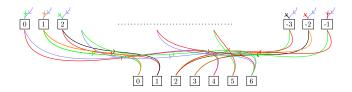


Figure 8: An illustration of between-hand processing. Note that the number of incoming edges to each terminal node in the last round is equal to the number of edges going from that node to the root-level node in the next round. However, the color may change, as the corresponding running-score tensor is added to each score inherited from previous rounds.

Note that this is an intermediate step: the final version of t_fgm will be updated later in the process. Next, we determine how scores are passed from one hand to the next. That is, we construct the new t_fgm[:,1] tensor for the upcoming round. Finally, we find unique rows in t_fgm as follows:

 t_{fgm} , $t_{lnk} \leftarrow unique(t_{fgm}, dim=0, sorted=False, return_inverse=True)$ CodeSnippet 7 summarizes the steps discussed above.

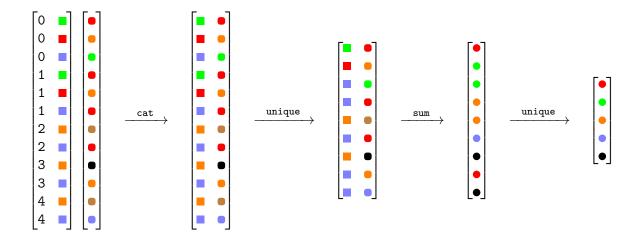


Figure 9: An illustration of between-hand updates for t_fgm.

2.8 Infoset Tensors

In this section, we represent FGT's nodes using the int8 Infoset Tensor t_inf, where each row has shape [58]. This tensor encodes all information available at that point in the game tree and can be easily adapted to mask any information not observable by the acting player. This design serves two primary purposes: first, to ensure memory efficiency; and second, to provide a compact representation of both the game state and associated action information. These representations are later used to train a tree-based model to approximate the strategy profile, which is

CodeSnippet 7 BetweenHands

subsequently used in self-play simulations, as described in Section 3. It is important to emphasize that these infoset tensors are used only after the Nash equilibrium has been learned using the CFR algorithm. Tensor t_inf consists of three distinct parts, summarized in Table 14 and CodeSnippet 8 explains its construction process.

Table 14: Index structure of the t_inf tensor

Index Range	Section	Description
0:52	Cards	Status/history of each card
52:55	Score context	Inherited scores such as club points and point differential
55:58	Metadata	Round index, turn counter, and current player indicator

CodeSnippet 8 Infoset Tensor

```
1: t_inf \( \times \text{zeros}((Q, 58)) \) # Q=t_fgm.shape[0]
2: t_inf[:, t_inp] \( \times t_cmp[t_fgm[:,0]] \)
3: t_inf[:,52:55] \( \times t_scr[t_fgm[:,1]] \)
4: t_inf[logical_and(t_dlt==1,t_inf==0)] \( \times -127 \) # for any dealt card represented in t_dlt & not present in t_gme, -127 is assigned i.e., card is collected in past rounds.
5: t_inf[:,55:58] \( \times tensor([i_hnd,i_trn,i_ply]) \)
```

2.9 External Sampling

In this section, we describe the procedure for external sampling used during the unfolding process. Although the present work does not rely on or develop specific sampling techniques, we include this explanation for the sake of completeness and future reference. The external sampling method outlined here will play a key role in subsequent extensions of this research, where sampling-based approaches will be more actively explored and integrated into the modeling framework.

In external sampling, a single action is selected for the opponent based on their

Game Tree Full Game Tree

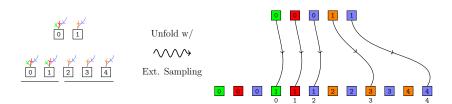


Figure 10: An illustration of how t_edg is constructed under ex. sampling regime.

current strategy. This selection is performed within FGT, as illustrated in Figure 10. To further aid understanding, Figure 11 illustrates how the FGT tensor t_fgm is updated/sampled. CodeSnippet 9 details the procedure used in external sampling.

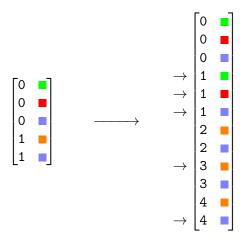


Figure 11: An illustration of how t_fgm is updated under ext. sampling regime.

CodeSnippet 9 ExternalSampling

```
1: Input t_edg,c_edg,t_sgm
   #t_edg links lower to upper nodes, while c_edg specifies the degree of each upper node.
   #Ex: t_{edg} = [0,1,2,0,1,2,3,4,3,4,3,4], c_{edg} = t_{brf} \otimes c_{scr} = [2,2,2,3,3]
 2: t_inv = argsort(t_edg, stable=True)
   \#t_{inv} = [0,3,1,4,2,5,6,8,10,7,9,11]
   #use t_inv when sorting edges.1st green maps to index 0, 2nd green maps to index 3, etc
3: t_idx = empty_like(t_inv)
 4: t_idx[t_inv] ← arange(len(t_inv))
   #t_idx =[ 0, 2, 4, 1, 3, 5, 6, 9, 7, 10, 8, 11]
   #use t_idx when mapping back sorted edges
 5: i_max = c_edg.max()
6: t_msk = arange(i_max).unsqueeze(0) < c_edg.unsqueeze(1)
   #t_msk = tensor([[ T, T, F], [ T, T, F], [ T, T, F], [ T, T, T], [ T, T, T]])
7: t_mtx = zeros_like(t_msk)
 8: t_mtx[t_msk] \leftarrow t_sgm[t_inv]
9: t_smp = multinomial(t_mtx).squeeze(1)
   #sampled indices for each row
10: t_gps = cat([0, c_edg.cumsum()[:-1]])
11: t_res = zeros_like(t_sgm, dtype=bool)
12: t_res[t_gps + t_smp] ← True
13: t_res \leftarrow t_res[t_idx]
```

2.10 CFR Algorithm

In this section, we provide details on the PyTorch implementation of CFR for Pasur, following the framework outlined in the previous sections.

Our approach is as follows: for each round, we compute the average utility at the root-level nodes of the FGT. This utility is then propagated backward to the preceding round, where CFR is applied to compute the utilities for that round's root-level nodes. While this process is underway within a round, we simultaneously compute the average strategy profile (Equation (5)) for that round.

It is important to emphasize that when working within a round, the reach probabilities for the root-level nodes are all set to 1. Since Pasur consists of six rounds, we apply the CFR algorithm six times—once per round. The utility for the final round is computed directly by calculating the final score. Notably, the running-score tensor t_rus is added to the utility of the final-layer nodes before applying CFR.

We treat utility values with equal weights, based on the logic that each unit of utility represents a point earned under the Nash Equilibrium at that terminal node within the round. Because t_rus reflects the points accumulated during that round, it is appropriate to add it linearly to the computed utility.

This round-by-round implementation is both more accurate and memory-efficient. First, by computing utilities one round at a time rather than propagating utilities from terminal nodes all the way to the top of the full game tree, we improve numerical stability. This localized computation reduces the accumulation of floating-point

errors that can arise when backpropagating through long sequences. Second, by isolating the computation to a single round at a time, we only need to move the relevant tensors for that round to the GPU, while keeping the rest on the CPU. Importantly, all tensors involved in our framework are stored on the CPU for use in the CFR algorithm. This design choice significantly reduces GPU memory pressure during training. As a result, we require significantly less GPU VRAM to compute the Nash Equilibrium. On the other hand, the main downside is the increased complexity in implementation and debugging, as computations must now be carefully coordinated across multiple rounds.

We begin by obtaining the final scores from FGT's terminal nodes. This can be achieved using the following:

Within CodeSnippet 7, we need to reverse Line (10) to recover t_utl at the terminal nodes. In other words, the t_utl tensor computed above can be interpreted as the root-level utility of the next round, which must be passed back to the terminal level of the current round. Once t_utl is obtained at the root level for each round, it should be propagated upward to the terminal nodes of the previous round and combined with the corresponding running-score tensor for each FGT node at that level. The following code accomplishes this:

$$t_rus = t_rus \otimes c_scr$$

$$t_utl = t_utl[t_lnk] + t_rus$$
(10)

Here t_lnk is defined in the final step of CodeSnippet 7 and t_rus appears in the same CodeSnippet, prior to being passed through unique in line 3.

The next three CodeSnippets present the CFR algorithm. There are two main components: the FindUtility and FindReachProbability functions. The overall CFR algorithm is shown in CodeSnippet 10.

CodeSnippet 10 CFR

```
1: function RUNCFR
       Compute g_utl # via Equation (9)
 3:
       for round in reversed (rounds) do
           g_utl \leftarrow Pass back up g_utl via Equation (10)
           Initialize g_reg, g_sgm, g_UTL
   \# g_reg (init. to 0): regrets for all the availble actions, r^t in Eq. (6),
   \# g_sgm (init. to uniform): strategy profile, \sigma^t in Eq. (4)
   \# g_UTL (init. to 0): root-node utilities for current round, R^t in Eq. (6)
           for t in range(NUM_ITER) do
               g\_rpr \leftarrow FINDRPR(g\_sgm)
 7:
               t_utl, g_sgm, a_sgm, g_reg 

FINDUTILITY(g_rpr, g_utl)
 8:
9:
               g\_UTL \leftarrow g\_UTL + t\_utl
           end for
10:
11:
           g_utl \leftarrow g_UTL/NUM_ITER
12:
           g\_sgm \leftarrow NORMALIZE(a\_sgm) \# Each FGT node's children's values sum to 1
       end for
13:
14: end function
```

CodeSnippet 11 FindReachProbability

```
1: function FINDRPR(g_sgm, i_cfr) # g_sgm:current round's strategy. \sigma^t in Eq. (4)
        i\_h \leftarrow \texttt{\# nodes in current round's root level}
 3:
        t\_rpr \leftarrow ones(i\_h)
        d_rpr \leftarrow \{\}
 4:
        for i_trn in range(4) do
 5:
            for i_ply in range(2) do
 6:
                i_htp \( \tilde{\text{i_hnd_i_trn_i_ply}} \)
 7:
                t_sgm \leftarrow g_sgm[i_htp]
8:
9:
                t\_sgm \leftarrow ones\_like(t\_sgm) if i\_ply == i\_cfr
                t_edg \leftarrow gt_edg[i_htp] \# CUDA tensors gt_edg contains FGT edges
10:
                d_rpr[i_htp] \leftarrow t_sgm * t_rpr[t_edg]
11:
                t_rpr \( \) d_rpr[i_htp]
12:
            end for
13:
        end for
14:
        return d_rpr
16: end function
```

CodeSnippet 12 FindUtility

```
1: function FINDUTILITY(t_utl, g_sgm, a_sgm, g_reg, g_rp0, g_rp1)
    # Input: gt_edg: FGT edges, gc_edg: FGT branch factor
    # TOL = 1e-5, a_sgm: average strategy, g_rp0, g_rp1: reach probs for Alex & Bob resp.
    # g_sgm: current strategy
        for i_trn in REVERSED(range(4)) do
           for i_ply in REVERSED(range(2)) do
 3:
 4:
               i_htp \leftarrow i_hnd_i_trn_i_ply
               i h \leftarrow \text{# nodes in current layer's root-level}
 5:
               t_ply, t_opp \( \) g_rp0[i_htp], g_rp1[i_htp] if i_ply == 1
 6:
               t_ply, t_opp \leftarrow g_rp1[i_htp], g_rp0[i_htp] if i_ply == 0
 7:
               c_edg,t_edg,t_sgm \( -gc_edg[i_htp], gt_edg[i_htp],g_sgm[i_htp] \)
 8:
               \texttt{t\_pt2} \leftarrow \texttt{zeros(i\_h)}
 9:
               t_pt2.scatter_add_(0,t_edg,t_sgm*t_utl)
10:
               t_reg \leftarrow (1-2*i_ply)*t_opp*(t_utl-t_pt2[t_edg])
11:
               \texttt{t\_utl} \leftarrow \texttt{t\_pt2}
12:
               t_msk \leftarrow g_reg[i_htp] >= TOL
13:
               t_fct \leftarrow zeros_like(g_reg[i_htp])
14:
               \texttt{t\_fct[t\_msk]} \leftarrow \texttt{i\_cnt**1.5/(1+i\_cnt**1.5)}
15:
               t_fct[~t_msk] \leftarrow 0.5
16:
17:
               g_reg[i_htp] \leftarrow t_fct*g_reg[i_htp]+t_reg
               t_rts ← clamp(1000*g_reg[i_htp], min=TOL)
18:
               t_sum \leftarrow zeros(i_h)
19:
               t_sum.scatter_add_(0, t_edg, t_rts)
20:
               t_msk \leftarrow t_sum[t_edg] \le TOL
21:
22:
               t_sgm[~t_msk] \lefta t_rts[~t_msk]/t_sum[t_edg][~t_msk]
               t_sgm[t_msk] \leftarrow (1/c_edg[t_edg])[t_msk]
23:
               a\_sgm[i\_htp] \leftarrow (1-1/(1+i\_cnt)**2)*a\_sgm[i\_htp] + t\_sgm*t\_ply
24:
               g_sgm[i_htp] \leftarrow t_sgm
25:
           end for
26:
        end for
27:
        return t_utl, a_sgm, g_sgm, g_reg
28:
29: end function
```

3 Experimental Evaluation

We trained more than 500 randomly generated decks using the CFR algorithm and obtain strategy profiles similar (stored in .parquete) to the one shown in Table 15. Figure 12 shows the distribution of the sizes of the resulting full game trees corresponding to the shapes of the strategy profile tables.

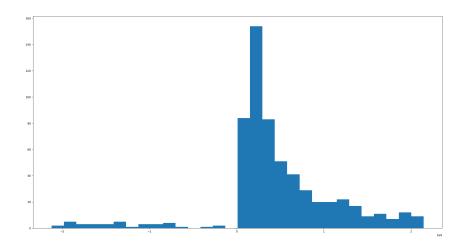


Figure 12: Distribution of game tree sizes (i.e., strategy profile table shapes) across 500 randomly generated decks.

We also illustrate a near-Nash equilibrium strategy, computed via CFR, in Figure 13 and Table 15. Figure 13 shows a sample game between two near-Nash strategies, while Table 15 lists their first-turn strategies in the first round.

Once we have the strategy profiles at our disposal, we fit an XGBoost model to predict $100 \times \sigma$, using root mean squared error (RMSE) as the evaluation metric and setting gamma=1 as the regularization parameter. This allows us to pass the current infoset to the model in order to obtain a near-Nash strategy for the active player. The main advantage of this approach is that it enables the simulation of multiple self-play games in parallel on the GPU. Specifically, if N denotes the number of self-play instances, then the infoset tensor at each turn has shape [N, 58]. Sampling based on the learned strategy profile is performed using the same method introduced in CodeSnippet 9.

With the ability to run multiple self-play games in parallel, we can now estimate the fair value of each deck composition. To do so, we let two near-Nash equilibrium strategies compete against each other using a given deck. The percentage of games won by Alex, divided by 100, is what we define as the fair value of that deck. As a first sanity check during development, we evaluated our model against a random strategy. Figure 14 presents the results: the left panel shows near-Nash vs. near-Nash, the middle panel shows near-Nash vs. Random, and the right panel shows Random vs. near-Nash.

Sample Game Played Between Near-Nash Strategies

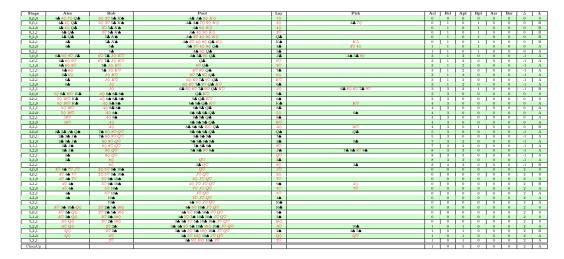


Figure 13: Some highlight of sound decisions made by both players: Since both players have full knowledge of each other's hands, Alex should avoid playing either $4\clubsuit$ or $4\diamondsuit$. Doing so would allow Bob to respond immediately by collecting $A\clubsuit$ and $A\spadesuit$ with his $5\clubsuit$, thereby securing 2 points and at least two clubs. Assuming instead that Alex plays $A\clubsuit$ and $A\spadesuit$ on his first move, Bob's optimal response is to collect using his $5\clubsuit$. Finally, if Alex plays $7\diamondsuit$, Bob should respond by picking up one Ace using either his $3\diamondsuit$ or $3\heartsuit$. It is emphasized that the strategy profile in Table 15 reflects all of these observations.

$A \clubsuit$	$A \spadesuit$	$3\diamondsuit$	3 %	4♣	$4\diamondsuit$	5♣	$7\diamondsuit$	$9\diamondsuit$	$Q \clubsuit$	$K\Diamond$	$K \spadesuit$	Н	Τ	Р	σ
110	110	105	105	100	1	105	100	110	100	110	105	0	0	0	0.00
110	110	105	105	1	100	105	100	110	100	110	105	0	0	0	0.00
110	110	105	105	100	100	105	1	110	100	110	105	0	0	0	1.00
110	110	105	105	100	100	105	100	110	1	110	105	0	0	0	1.00
110	110	105	-1	100	1	105	100	110	100	110	105	0	0	1	0.00
110	110	-1	105	100	1	105	100	110	100	110	105	0	0	1	0.00
-10	-10	105	105	100	-9	109	100	110	100	110	105	0	0	1	1.00
110	110	105	105	100	1	105	100	110	100	-10	109	0	0	1	0.00
110	110	-1	105	1	100	105	100	110	100	110	105	0	0	1	0.00
110	110	105	-1	1	100	105	100	110	100	110	105	0	0	1	0.00
110	110	105	105	1	100	105	100	110	100	-10	109	0	0	1	0.00
-10	-10	105	105	-9	100	109	100	110	100	110	105	0	0	1	1.00
110	110	105	105	100	100	105	1	110	100	-10	109	0	0	1	0.00
110	-10	109	105	100	100	105	-9	110	100	110	105	0	0	1	0.25
-10	110	105	109	100	100	105	-9	110	100	110	105	0	0	1	0.25
110	110	105	105	100	100	-1	1	110	100	110	105	0	0	1	0.00
-10	110	109	105	100	100	105	-9	110	100	110	105	0	0	1	0.25
110	-10	105	109	100	100	105	-9	110	100	110	105	0	0	1	0.25
110	110	-1	105	100	100	105	100	110	1	110	105	0	0	1	0.00
110	110	105	105	100	100	105	100	110	1	-10	109	0	0	1	1.00
110	110	105	105	100	100	-1	100	110	1	110	105	0	0	1	0.00
110	110	105	-1	100	100	105	100	110	1	110	105	0	0	1	0.00

Table 15: Near-Nash strategies for first turn of Figure 13's deck

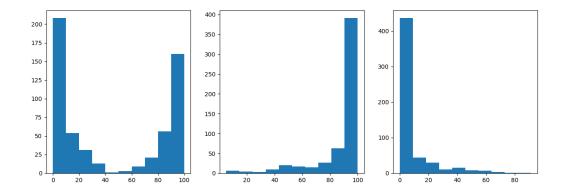


Figure 14: Left panel shows near-Nash vs. near-Nash, middle panel shows near-Nash vs. Random, and the right panel shows Random vs. near-Nash

# J	# ♣	v	std
= 0	≤ 7	0.06	0.03
= 0	> 7	0.22	0.11
= 1	≤ 5	0.06	0.02
= 1	>5	0.25	0.12
= 2	≤ 6	0.36	0.15
= 2	> 6	0.54	0.17
= 3	≤ 5	0.58	0.15
= 3	>5	0.76	0.10
= 4	≤ 4	0.66	0.11
= 4	>4	0.85	0.09

Table 16: Deck fair values vs. Jacks and Clubs held by Alex.

Another step in our analysis is to relate the fair value of a deck to key elements of its composition. For example, it is clear that holding Jack cards or Club cards provides a strategic advantage to the player. To investigate this relationship, we fit decision trees to subsets of decks, each categorized by the number of Jack cards held by Alex. We then examine how the decision tree branches based on the number of Clubs held by Alex. Table 16 illustrates this relationship: the more Jacks or Clubs Alex holds, the higher the fair value of the deck tends to be; providing supporting evidence that our CFR algorithm has converged to near-Nash equilibrium strategies.

We next examine the convergence behavior of CFR. To this end, we measure the mean squared error (MSE) between each intermediate strategy profile $\bar{\sigma}^t$ and the final CFR strategy vector. Since our approach computes strategies on a round-by-round basis, we provide separate plots for each round to visualize the convergence. It is important to note that, as shown in CodeSnippet 12, we use the DCFR algorithm from [2] with the following parameters:

$$\gamma = 2$$
, $\alpha = 1.5$, $\beta = 0$.

Figure 15 shows the CFR convergence behavior. Finally, Figure 16 shows the σ value for the first turn of Alex for Deck of Figure 13.

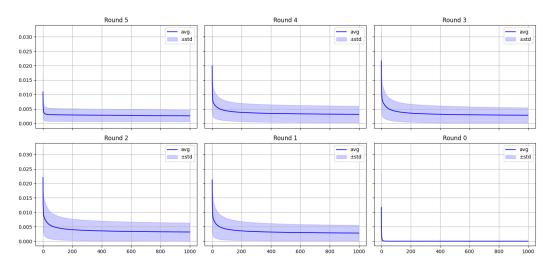


Figure 15: Convergence of CFR for 500 random decks. The plot shows the average \pm standard deviation bands of the mean squared error (MSE) to the final CFR vector, measured separately for each round. As observed, the last round converges the fastest due to having the fewest nodes in the FT representation.

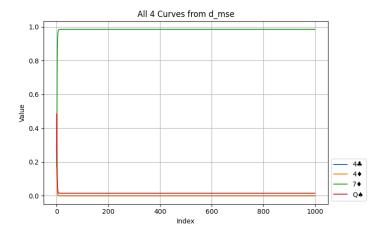


Figure 16: σ values for Alex's first turn using the deck from Figure 13

4 Future Work

We conclude the paper by outlining two promising directions for future research.

First, we need to extend the current framework to the more realistic and challenging setting where players do not have access to the opponent's hand information. This extension could proceed in two stages. First, the possible opponent deck compositions can be narrowed down to a small set of plausible candidates. Then, leveraging the external sampling technique introduced in Section 2.9, one could apply methods similar to those proposed in [1] to train general tree-based models and use CFR to solve Pasur in the most general setting. The development and evaluation of this more general framework are left to future work.

Second, it would be valuable to investigate whether a single XGBoost model can be trained to generalize across multiple strategy profiles. This investigation remains within the setting where both players have full knowledge of each other's hands, with the added complexity that multiple deck decompositions may be possible and gradually revealed as the game progresses. A key challenge in this context arises when decks share partial similarity—for example, two decks may have identical first-round compositions but differ in later rounds. Such differences can influence strategies even in the early stages, causing the same information sets to map to different actions. To address this, strategy training must account for this additional source of randomness.

Finally, another important direction for future work is to approximate the exploitability of the strategies trained in this paper. This would help validate convergence toward a true Nash equilibrium. Exploitability quantifies how far a strategy profile deviates from equilibrium, lower values indicate closer approximation to optimal play. A natural starting point would be the simplified setting where both players have full knowledge of each other's hands. Once exploitability is well-understood in this restricted scenario, approximation techniques can be applied to the general case to estimate the exploitability of the learned strategies.

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5 Appendix: RepeatBlocks

RepeatBlocks is a generalization of torch.repeat_interleave in which, instead of repeating individual elements, entire blocks of elements are repeated. Each block has a custom size and a custom repetition count. The idea is best explained through an example. Consider the following

$$t_{org} = [1,2,3,4,5,6], t_{bsz} = [2,3,1], t_{rpt} = [1,3,2]$$

Here $t_{\tt org,t_bsz,t_rpt}$ are the input tensor, block sizes, and repeat counts respectively. The desired output denoted by $t_{\tt org} \otimes_{t_{\tt bsz}} t_{\tt rpt}$ is

$$t_{-org} \otimes_{t_{-bsz}} t_{-rpt} = [1, 2, 3, 4, 5, 3, 4, 5, 3, 4, 5, 6, 6]$$

For convenience, let us denote $t_rbk = t_{org} \otimes_{t_bsz}t_{rpt}$. To construct t_rbk , it suffices to build the corresponding index tensor t_idx .

$$t_idx = [0, 1, 2, 3, 4, 2, 3, 4, 2, 3, 4, 5, 5]$$

Note that t_rbk = t_org[t_idx]. Next, consider the corresponding start indices of each repeated block

$$t_blk = [0, 0, 2, 2, 2, 2, 2, 2, 2, 2, 5, 5],$$

It is emphasized that using input tensors, t_blk is given as below.

$$t_blk = (cat([0,t_bsz[:-1]]) \otimes t_rpt) \otimes (\underbrace{t_bsz\otimes t_rpt}_{:=t_bls})$$

Deducting t_blk from t_idx, we arrive at the following tensor.

$$t_{pos} = [0, 1, 0, 1, 2, 0, 1, 2, 0, 1, 2, 0, 0]$$

Next,

arange($t_blk.shape[0]$)- $t_pos = [0, 0, 2, 2, 2, 5, 5, 5, 8, 8, 8, 11, 12]$ where a simple examination shows that the RHS is equal

$$cumsum(cat([0, t_bls[:-1]]))\otimes t_bls.$$

Putting pieces together, we arrive at Algorithm 13.

CodeSnippet 13 RepeatBlocks

```
1: Input t_org, t_bsz, t_rpt
   # t_org:input tensor, t_bsz:blocks sizes, t_rpt:repeat counts
   \# \text{ Ex: t_org} = [1,2,3,4,5,6], \text{ t_bsz} = [2,3,1], \text{t_rpt} = [1,3,2]
2: t_bgn \leftarrow cat([0,t_bsz[:-1]])\otimes t_rpt
   # Compute beginning indices of each output's block
   \# Ex: t_bgn = [0, 2, 2, 2, 5, 5]
3: t_bls \leftarrow t_bsz \otimes t_rpt
   # Compute sizes of each output's block
   \# Ex: t_bls = [2, 3, 3, 3, 1, 1]
4: t_blk \leftarrow t_bgn\otimes t_bls
   \# t\_blk[i] = j i.e., output[i] belongs to block j
   \# Ex: t_blk = [0, 0, 2, 2, 2, 2, 2, 2, 2, 2, 2, 5, 5]
5: t_csm \leftarrow cumsum(0,t_bls[:-1]) \otimes t_bls
   # Ex: t_csm=[ 0, 2, 5, 8, 11, 12] \&t_bls=[ 0, 0, 2, 2, 2, 5, 5, 5, 8, 8, 8, 11, 12]
6: t_pos ← arange(i_blk)-t_csm
   # Ex: t_pos=[0, 1, 0, 1, 2, 0, 1, 2, 0, 1, 2, 0, 0]
7: \ \texttt{t\_idx} \leftarrow \texttt{t\_pos+t\_blk}
   # Ex: t_idx=[0, 1, 2, 3, 4, 2, 3, 4, 2, 3, 4, 5, 5]
8: t_rbk \leftarrow t_org[t_idx]
   # Ex: t_rbk=[1, 2, 3, 4, 5, 3, 4, 5, 3, 4, 5, 6, 6]
9: Output t_rbk
   \# denoted by t\_org \otimes_{t\_bsz} t\_rpt
```