

Exercise 10.4 (Original Hull-White two-factor model)

Hull-White two-factor model was originally defined as

$$\begin{aligned} dU(t) &= -\lambda_1 U(t)dt + \sigma_1 d\tilde{B}_2(t) \\ dR(t) &= [\theta(t) + U(t) - \lambda_2 R(t)] dt + \sigma_2 d\tilde{B}_1(t). \end{aligned}$$

Here $\lambda_1, \lambda_2, \sigma_1, \sigma_2$ are positive constants. $\theta(t)$ is non-random function and $d\tilde{B}_1(t)d\tilde{B}_2(t) = \rho dt$. Derive a formula for $R(t)$ as below

$$R(t) = \delta_0(t) + \delta_1 Y_1(t) + \delta_2 Y_2(t).$$

Here canonical two-factor Vasicek equations hold in vector form as follows

$$dY(t) = -\Lambda Y(t) + d\tilde{W}(t).$$

Proof

Denote

$$\begin{aligned} X(t) &= \begin{bmatrix} U(t) \\ R(t) \end{bmatrix} \\ K &= \begin{bmatrix} \lambda_1 & 0 \\ -1 & \lambda_2 \end{bmatrix} \\ \Sigma &= \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix} \\ \Theta(t) &= \begin{bmatrix} 0 \\ \theta(t) \end{bmatrix} \\ \tilde{B}(t) &= \begin{bmatrix} \tilde{B}_1(t) \\ \tilde{B}_2(t) \end{bmatrix} \end{aligned}$$

Then

$$dX(t) = \Theta(t)dt - KX(t)dt + \Sigma d\tilde{B}(t).$$

Denote

$$\hat{X}(t) = X(t) - e^{-Kt} \int_0^t e^{Ku} \Theta(u) du.$$

We have that

$$\begin{aligned} d\hat{X}(t) &= dX(t) + Ke^{-Kt} \int_0^t e^{Ku} \Theta(u) dudt - \Theta(t)dt \\ &= -KX(t)dt + \Sigma d\tilde{B}(t) + Ke^{-Kt} \int_0^t e^{Ku} \Theta(u) dudt \\ &= -K \left[X(t)dt - e^{-Kt} \int_0^t e^{Ku} \Theta(u) du \right] dt + \Sigma d\tilde{B}(t) \\ &= -K\hat{X}(t) + \Sigma d\tilde{B}(t). \end{aligned}$$

Next, we find a matrix C such that

$$\tilde{W}(t) := C\Sigma\tilde{B}(t)$$

contains two independent Brownian motions $\tilde{W}_1(t)$ and $\tilde{W}_2(t)$. Since $\tilde{B}_i(t)$ is a martingale and linear combinations of martingales are martingales, we conclude that for any 2×2 matrix C , $\tilde{W}_i(t)$ is martingale for $i = 1, 2$. According to Levy theorem, it suffices to ensure that

$$d\tilde{W}_i(t)d\tilde{W}_j(t) = \delta_{i,j}dt.$$

Rewriting, this is equivalent to

$$d\tilde{W}(t)d\tilde{W}(t)^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} dt$$

Notice

$$\begin{aligned} d\tilde{W}(t)d\tilde{W}(t)^T &= C\Sigma d\tilde{B}(t)d\tilde{B}(t)^T \Sigma^T C^T \\ &= C\Sigma \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \Sigma^T C^T dt \end{aligned}$$

Let

$$C = \begin{bmatrix} \frac{1}{\sigma_1} & 0 \\ -\frac{\rho}{\sigma_1\sqrt{1-\rho^2}} & \frac{1}{\sigma_2\sqrt{1-\rho^2}} \end{bmatrix}$$

Then

$$C\Sigma = \begin{bmatrix} 1 & 0 \\ -\frac{\rho}{\sqrt{1-\rho^2}} & \frac{1}{\sqrt{1-\rho^2}} \end{bmatrix}$$

Continuing,

$$\begin{aligned} C\Sigma \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \Sigma^T C^T dt &= \begin{bmatrix} 1 & 0 \\ -\frac{\rho}{\sqrt{1-\rho^2}} & \frac{1}{\sqrt{1-\rho^2}} \end{bmatrix} \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \begin{bmatrix} 1 & -\frac{\rho}{\sqrt{1-\rho^2}} \\ 0 & \frac{1}{\sqrt{1-\rho^2}} \end{bmatrix} dt \\ &= \begin{bmatrix} 1 & \rho \\ 0 & \sqrt{1-\rho^2} \end{bmatrix} \begin{bmatrix} 1 & -\frac{\rho}{\sqrt{1-\rho^2}} \\ 0 & \frac{1}{\sqrt{1-\rho^2}} \end{bmatrix} dt \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} dt. \end{aligned}$$

Denote

$$Y(t) = C\hat{X}(t).$$

Then

$$\begin{aligned} dY(t) &= -\underbrace{CKC^{-1}C}_{:=\Lambda} \hat{X}(t) + C\Sigma d\tilde{B}(t) \\ &= -\Lambda Y(t) + d\tilde{W}(t). \end{aligned}$$

Denote

$$[\delta_1, \delta_2] := [0, 1]C^{-1}.$$

Then

$$\begin{aligned} R(t) - \underbrace{e^{-Kt} \int_0^t e^{Ku} \theta(u) du}_{:=\delta_0(t)} &= [0, 1] \hat{X}(t) \\ &= [\delta_1, \delta_2] C \hat{X}(t) \\ &= [\delta_1, \delta_2] Y(t) \end{aligned}$$

Rewrite to get

$$R(t) = \delta_0(t) + \delta_1 Y_1(t) + \delta_2 Y_2(t).$$